

# High strain rate photomechanics on composites: use of a ultra high speed camera and the virtual fields method

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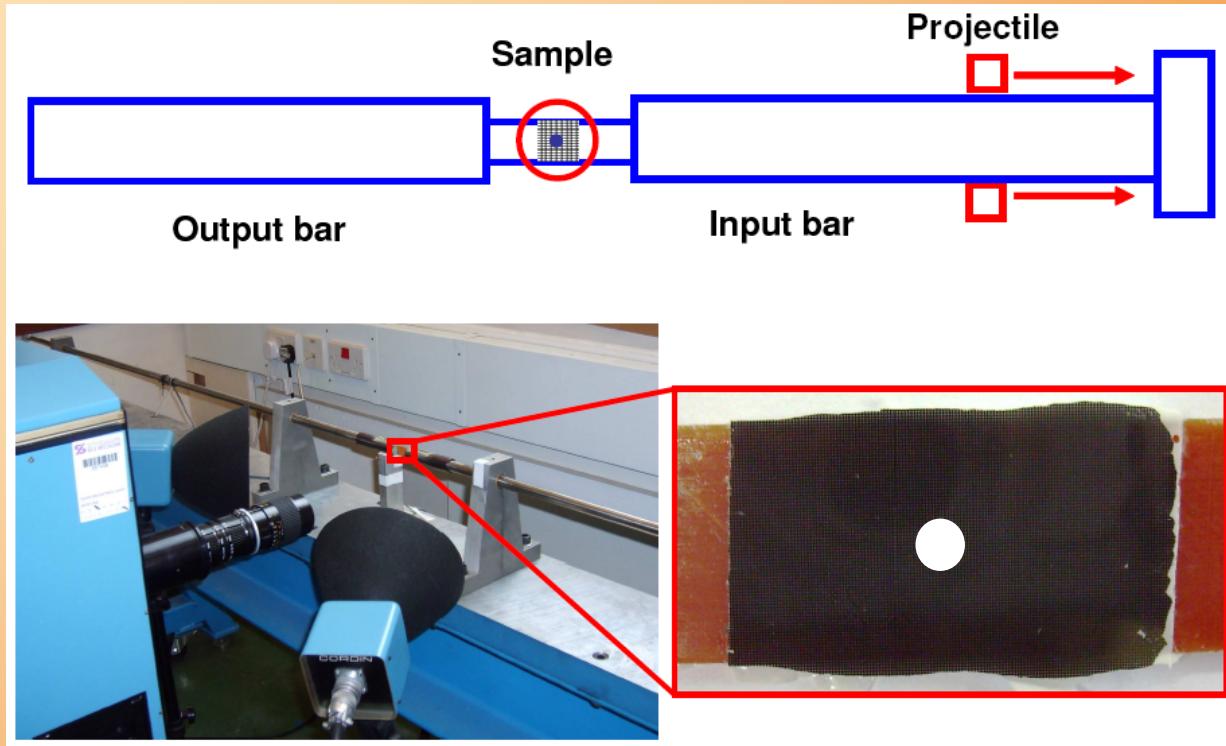
ACCIS, Aerospace Engineering,  
University of Bristol, UK



# Objectives

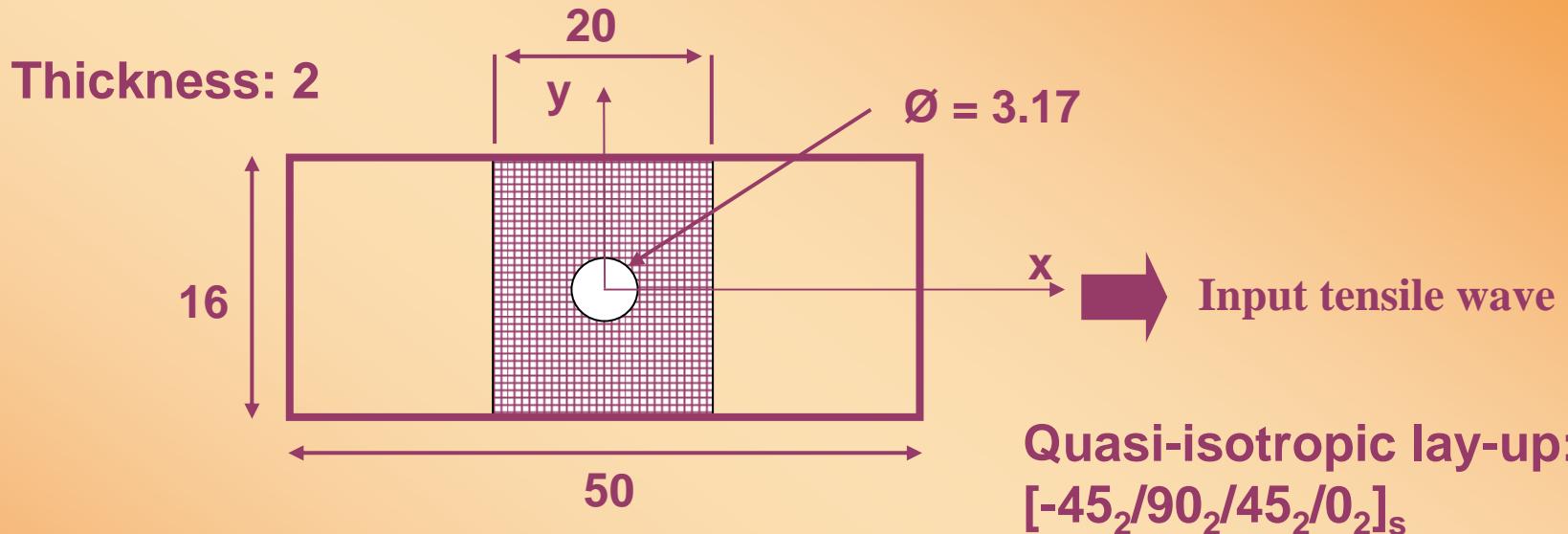
- Perform full-field deformation measurements with a ultra high speed camera
  - Evaluate performances (quantitative measurements)
- Process the deformation data to identify stiffnesses
  - Use of acceleration maps to make up for the lack of force data

# Test set-up



# Test set-up

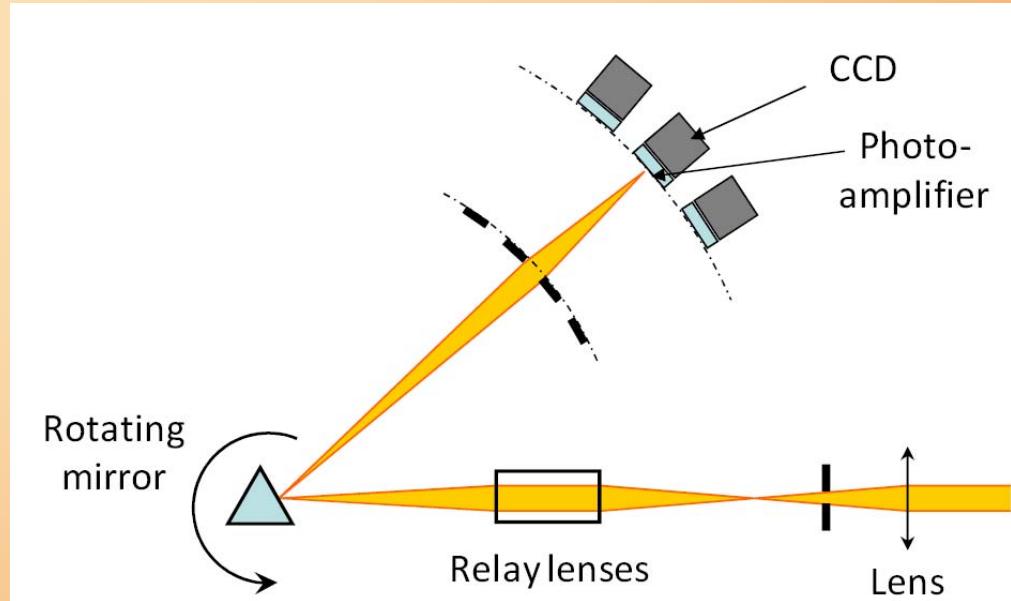
- Test specimen: glass-epoxy composite



- Cross-line grid: 200  $\mu\text{m}$  pitch
  - Transferred onto specimen
  - Displacements obtained by spatial phase shifting

# Test set-up

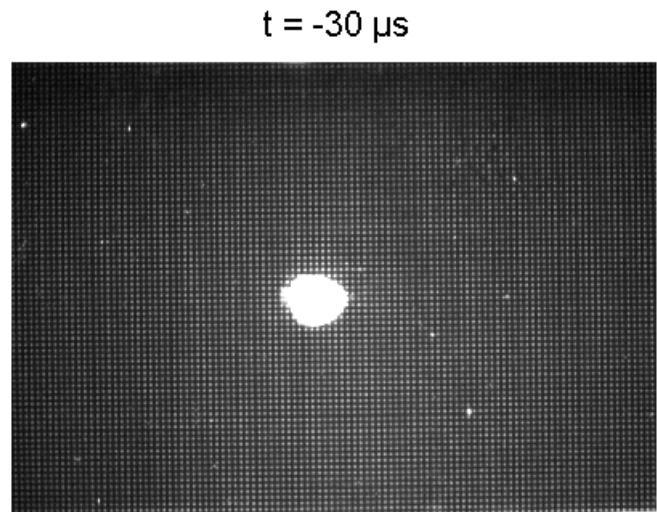
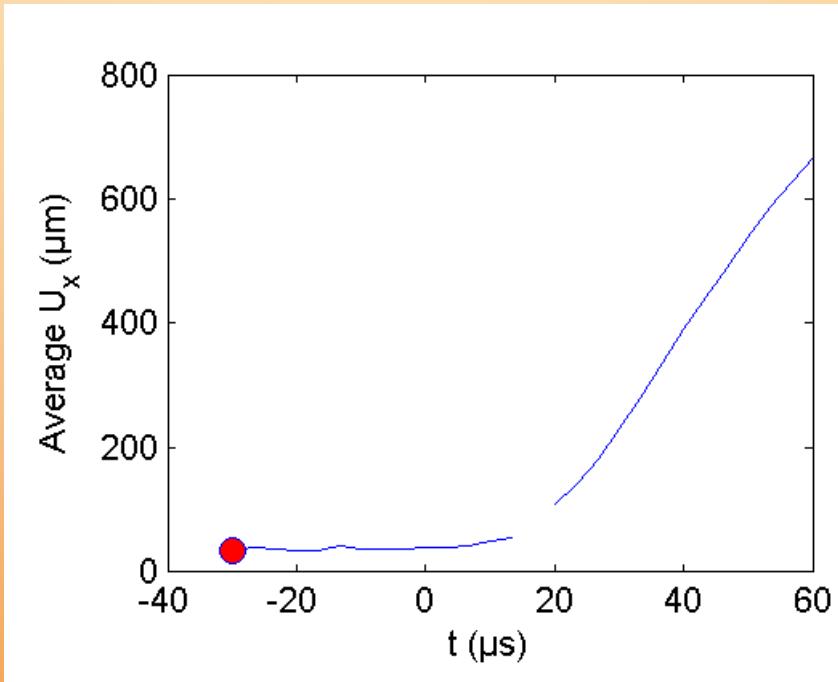
- Ultra high speed camera: Cordin 550-62



- Time resolution:  $3.3 \mu\text{s}$  (300.000 fps) – light issues
  - Maximum frame rate: 4 Mfps!
- Spatial resolution: 1 Mpixel

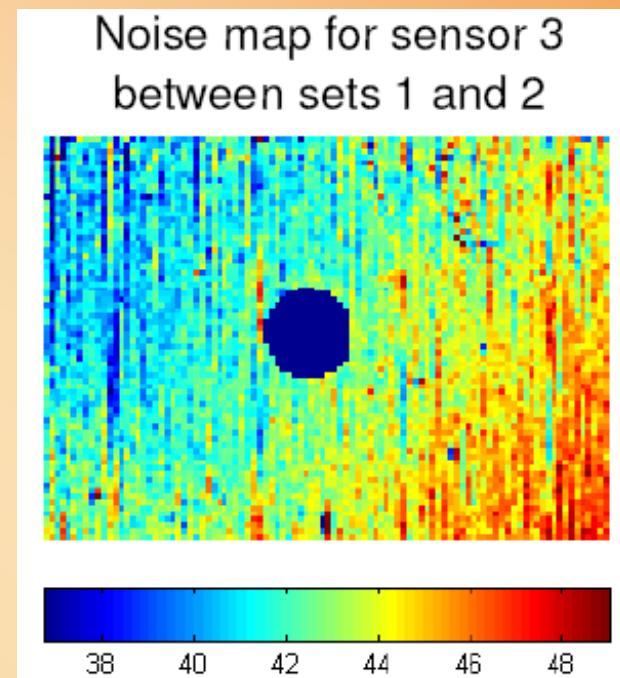
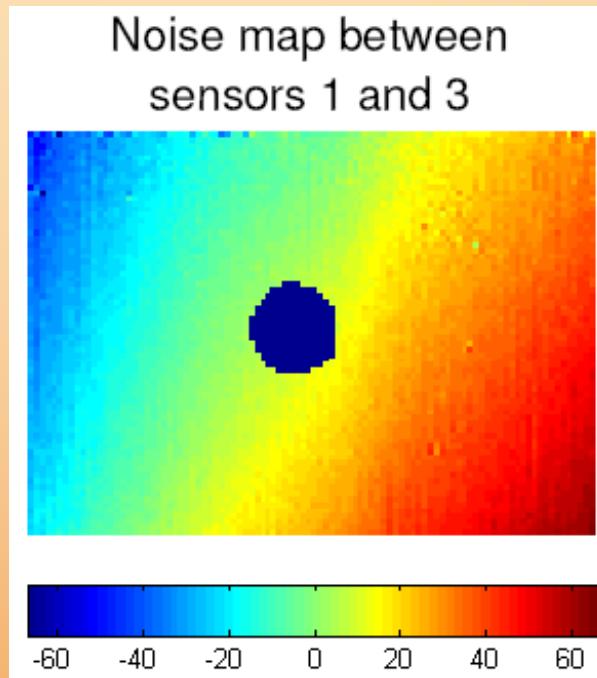
# Measurements

- Grey level images



# Measurements

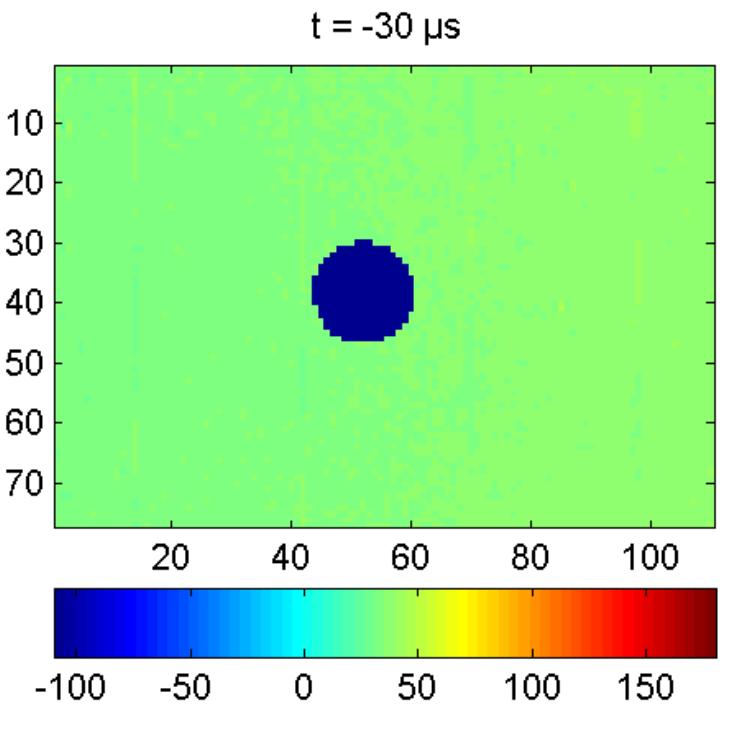
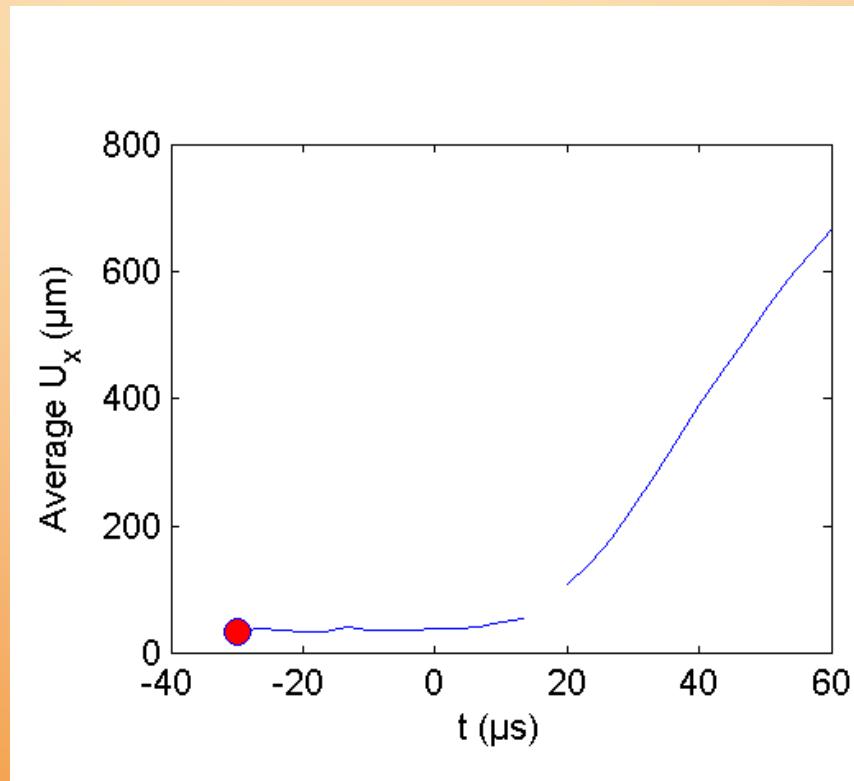
- Problem of bias caused by sensor positions



- Need for a first set of 62 still images
- Phase maps obtained sensor by sensor
- Final resolution: 5  $\mu\text{m}$  (2.5% of grid pitch)

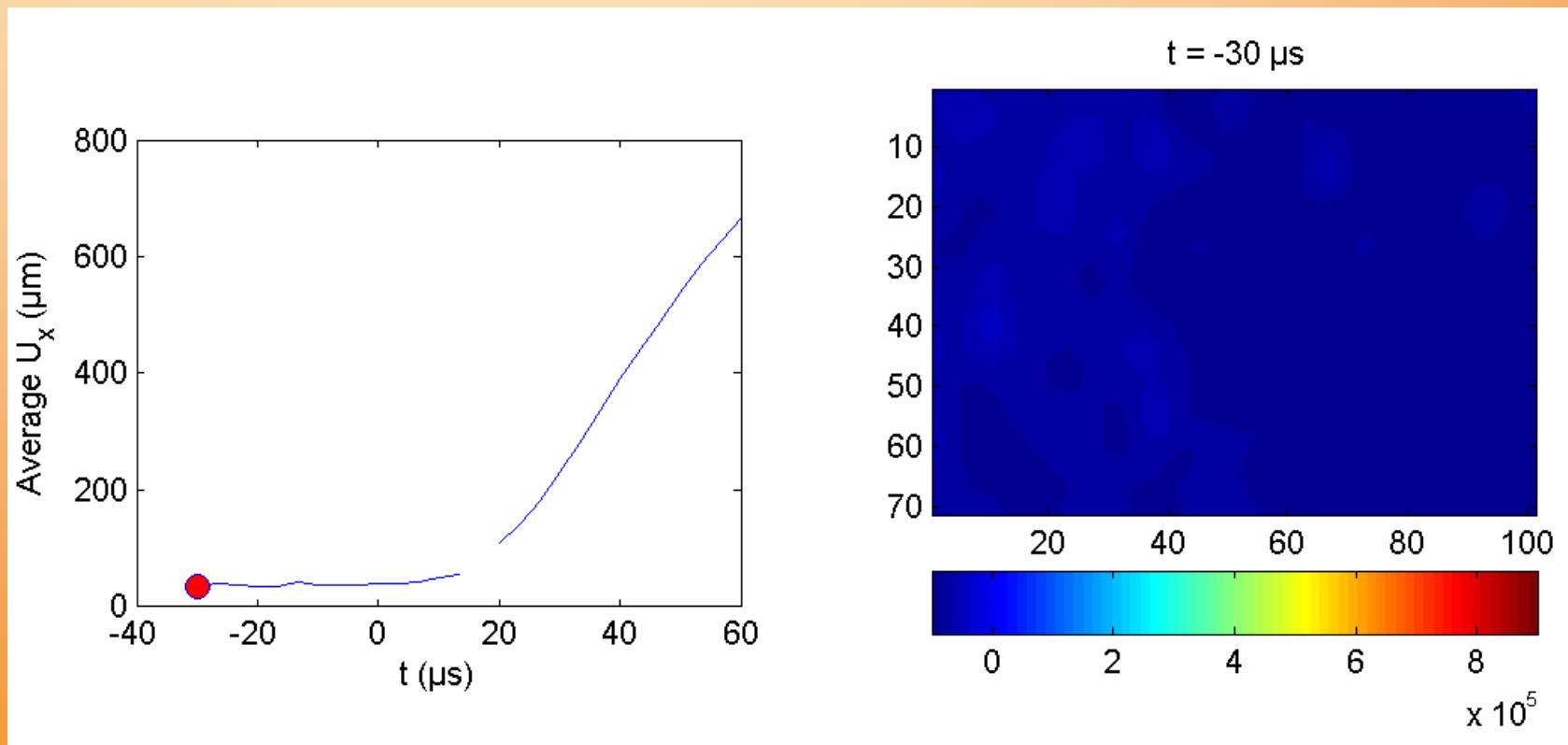
# Measurements

- Longitudinal displacement



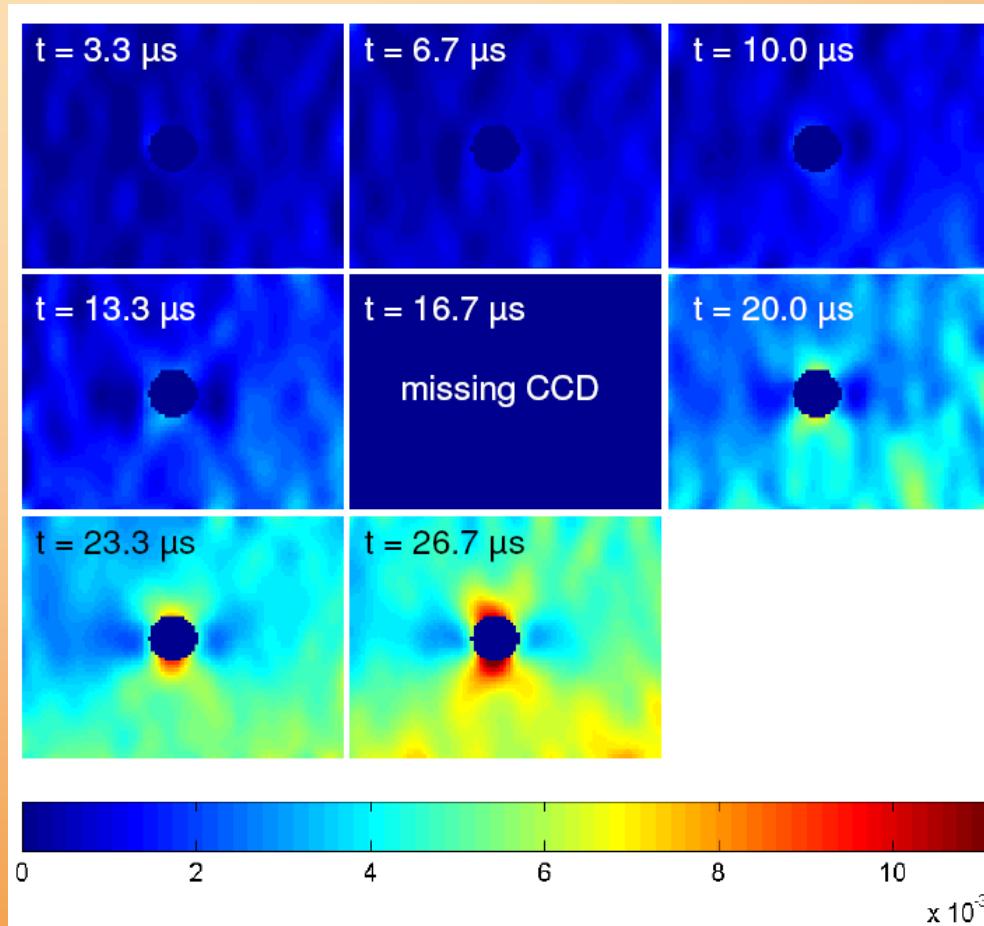
# Measurements

- Acceleration maps: double temporal differentiation
  - 4<sup>th</sup> order polynomial fit over time
  - Sliding window of 9 images
  - Resolution: between 1 and  $2.10^5 \text{ m.s}^{-2}$



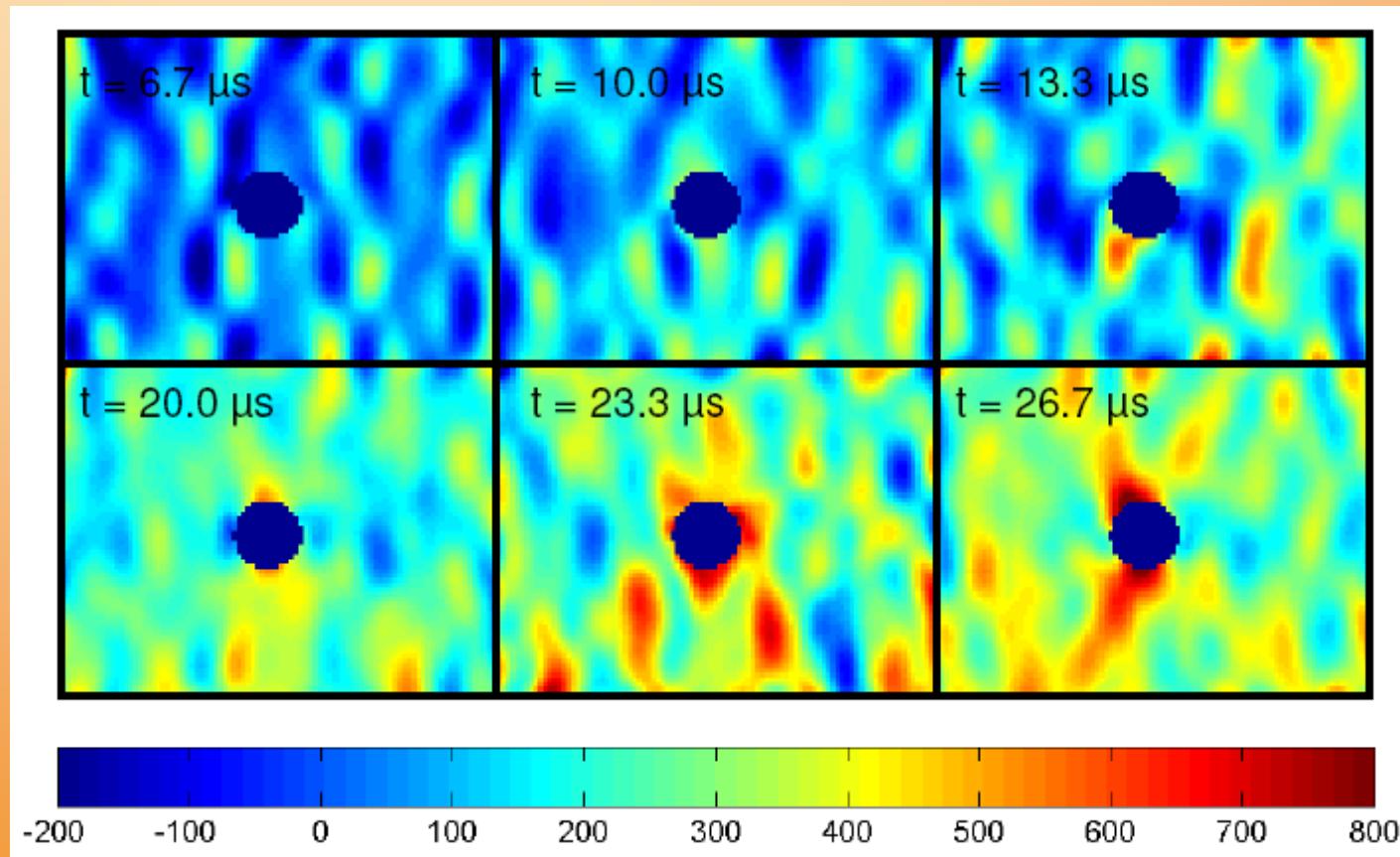
# Measurements

- Strain maps: spatial differentiation
  - Local smoothing (diffuse approximation)
  - Resolution:  $10^{-3}$

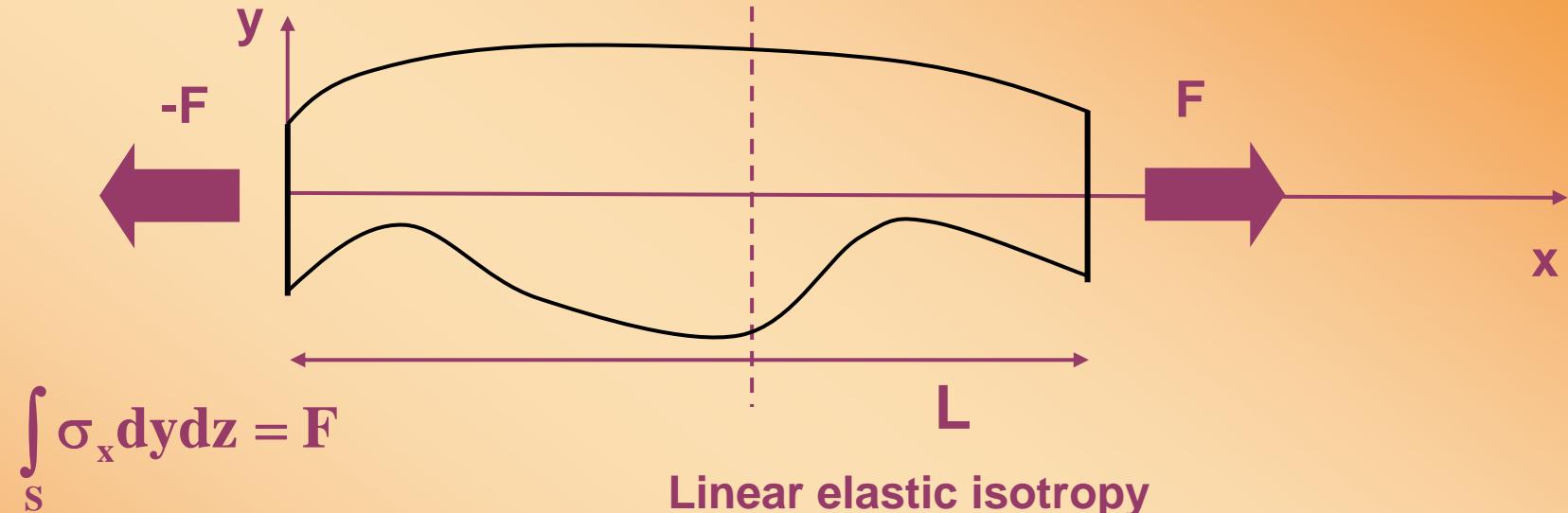


# Measurements

- Strain rate maps ( $\text{s}^{-1}$ ): temporal differentiation
  - Calculated through point to point finite difference
  - Resolution: about 400  $\text{s}^{-1}$



- The virtual fields method



Integrate over x

$$\int_V \sigma_x dx dy dz = FL$$

Plane stress

$$\int_S \sigma_x dx dy = \frac{FL}{t}$$

$$\int_S (Q_{xx} \varepsilon_x + Q_{xy} \varepsilon_y) dx dy = \frac{FL}{t}$$

Homogeneous material

$$Q_{xx} \int_S \varepsilon_x dx dy + Q_{xy} \int_S \varepsilon_y dx dy = \frac{FL}{t}$$

- Principle of virtual work

$$-\int_V \sigma : \varepsilon^* dV + \int_{\partial V} T \cdot u^* dS = \int_V \rho a \cdot u^* dV \quad 1 \text{ VF: 1 linear equation}$$

- No force measurement

➤ In “static”:

$$\int_V \sigma : \varepsilon^* dV = 0 \quad [A]\{Q\} = \{0\}$$

◆ Only stiffness ratios ( $\nu$ )

- No force measurement

➤ In dynamic

$$-\int_V \sigma : \varepsilon^* dV = \int_V \rho a \cdot u^* dV$$

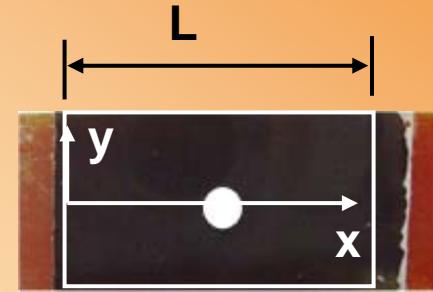
◆ Acceleration forces: distributed volumic load cell!

# Identification

- Choice of virtual fields: field 1

$$\begin{cases} \mathbf{u}_x^* = x(x - L) \\ \mathbf{u}_y^* = 0 \end{cases}$$

$$\begin{cases} \varepsilon_x^* = 2x - L \\ \varepsilon_y^* = 0 \\ \varepsilon_s^* = 0 \end{cases}$$



$$\int_{\partial V} T \cdot u^* dS = 0$$

$$Q_{xx} \int_S (2x - L) \varepsilon_x^* dx dy + Q_{xy} \int_S (2x - L) \varepsilon_y^* dx dy = -\rho \int_S x(x - L) a_x^* dS$$

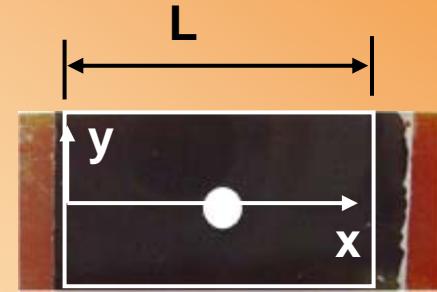
Spatial differentiation  
of  $U_x$

Spatial differentiation  
of  $U_y$

Double time  
differentiation  
of  $U_y$

- Choice of virtual fields: field 2

$$\begin{cases} \mathbf{u}_x^* = \mathbf{0} \\ \mathbf{u}_y^* = x(x-L)y \end{cases} \quad \begin{cases} \varepsilon_x^* = 0 \\ \varepsilon_y^* = x(x-L) \\ \varepsilon_s^* = (2x-L)y \end{cases}$$



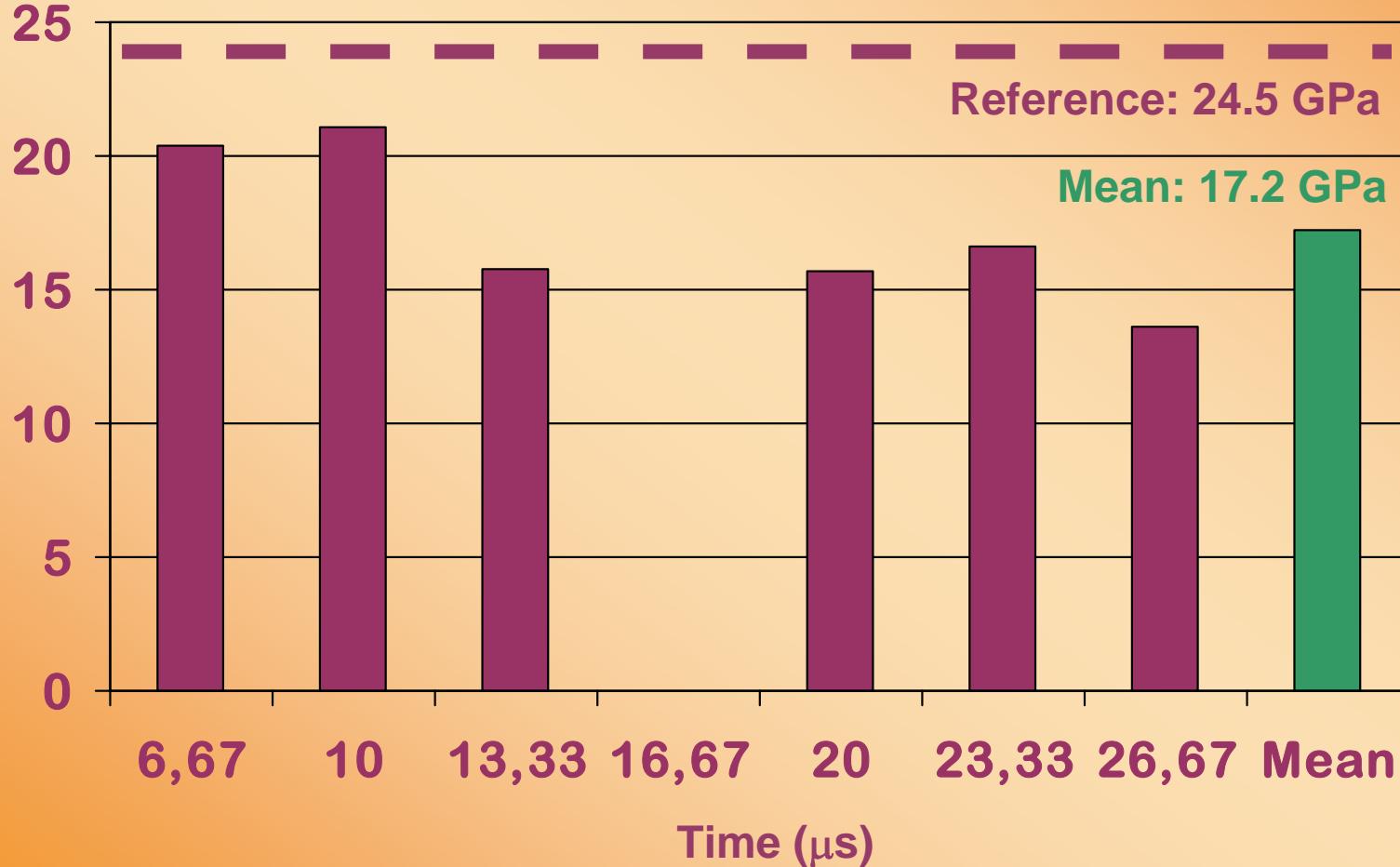
$$Q_{xx} \int_S \left( x(x-L)\varepsilon_y + \frac{1}{2}(2x-L)y\varepsilon_s \right) dx dy + \\ Q_{xy} \int_S \left( x(x-L)\varepsilon_x - \frac{1}{2}(2x-L)y\varepsilon_s \right) dx dy = -\rho \int_S x(x-L)y a_y dS$$

Linear system  $[A]\{Q\} = \{B\}$

[www.camfit.fr](http://www.camfit.fr)

- Results

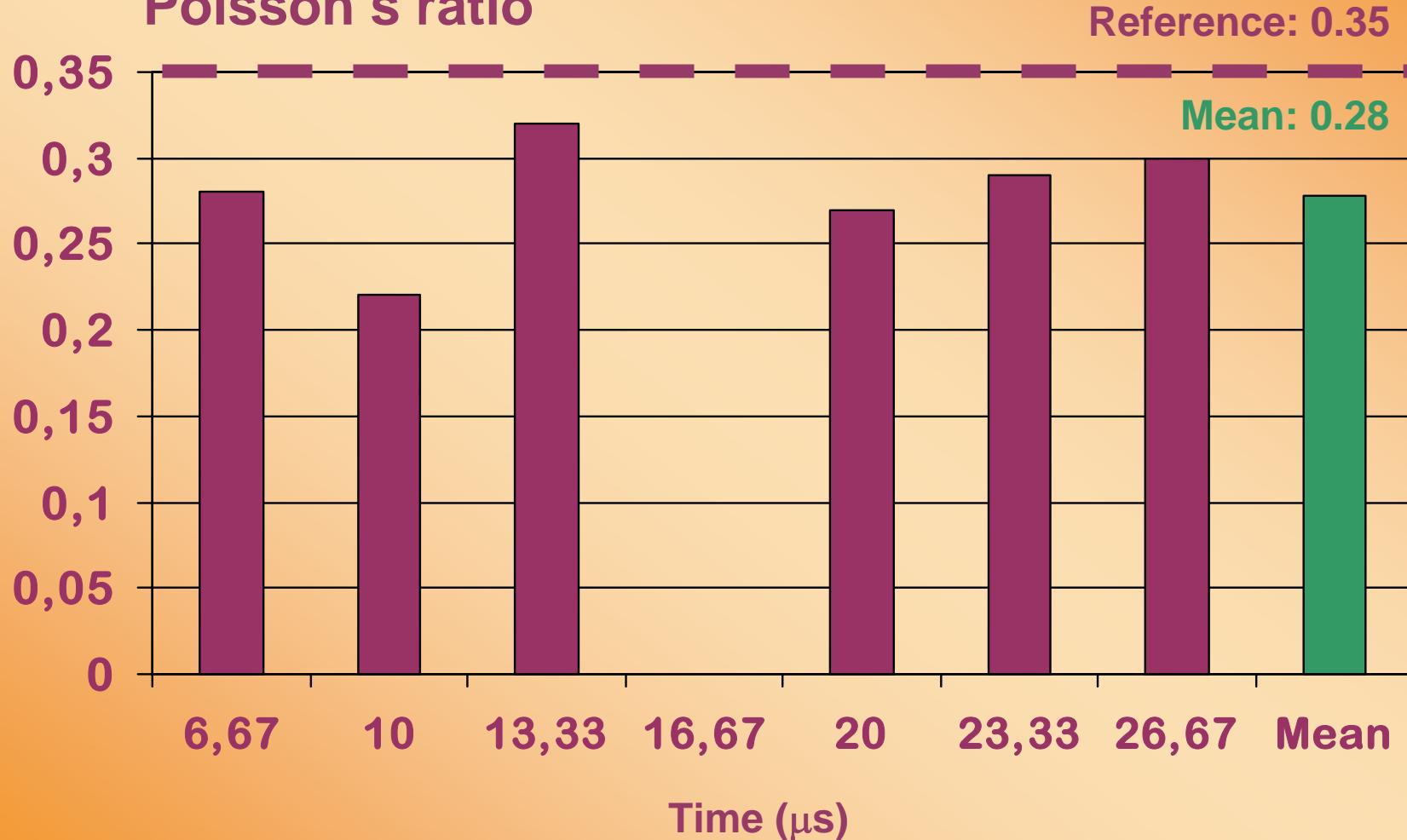
## Young's modulus (GPa)



- Results

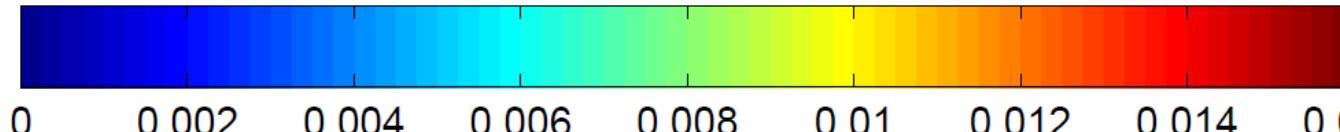
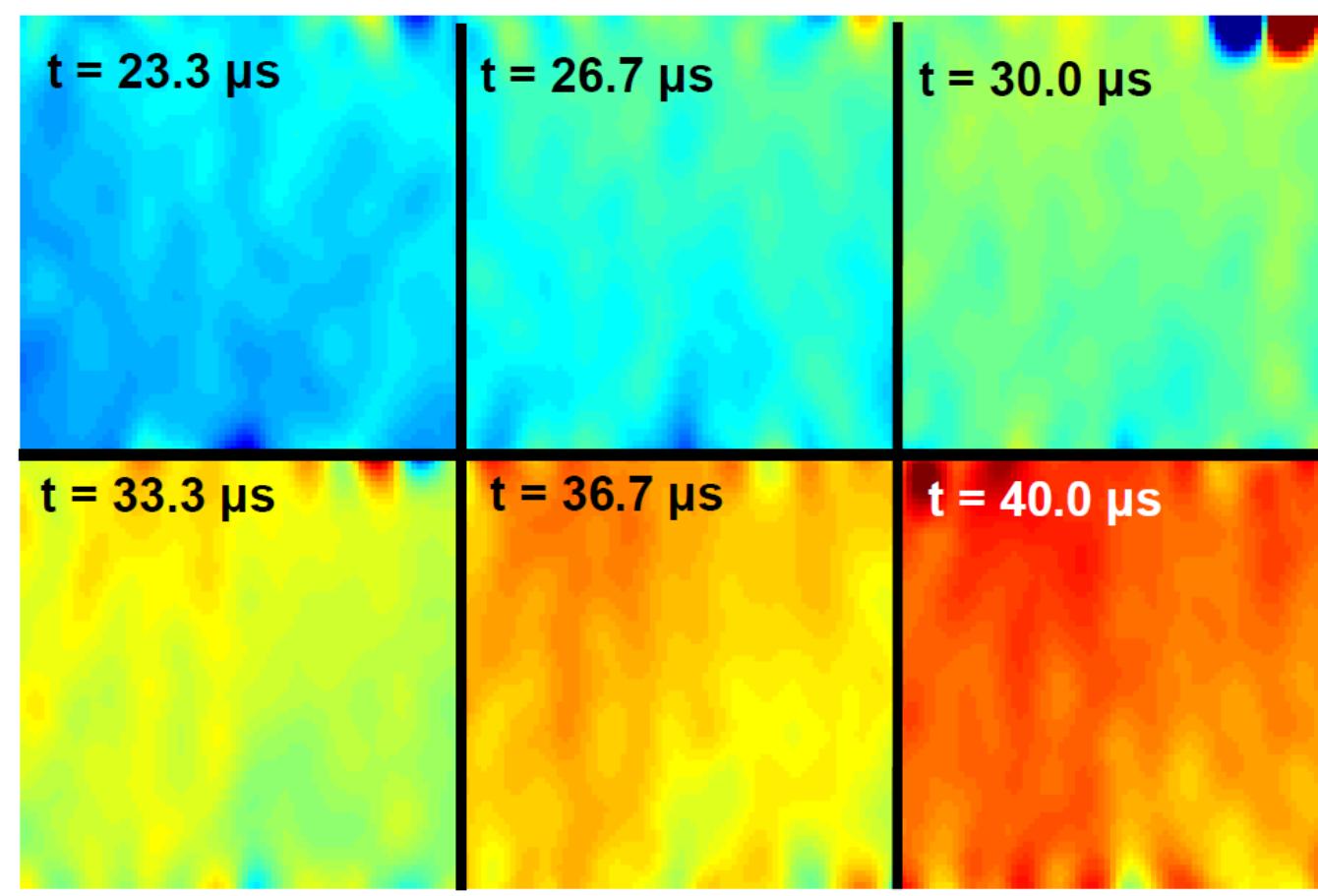
## Poisson's ratio

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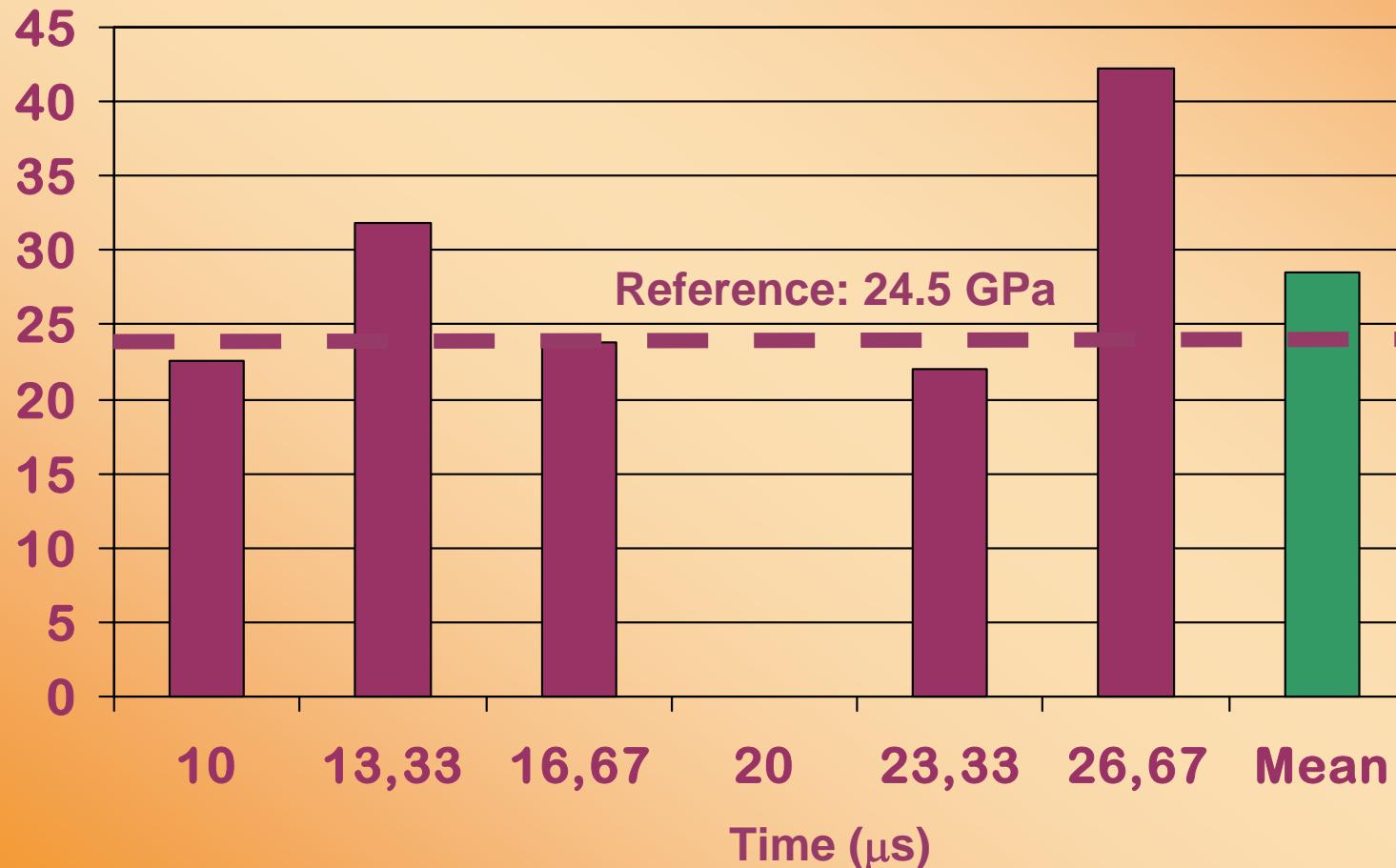
# Identification

- Specimen without a hole



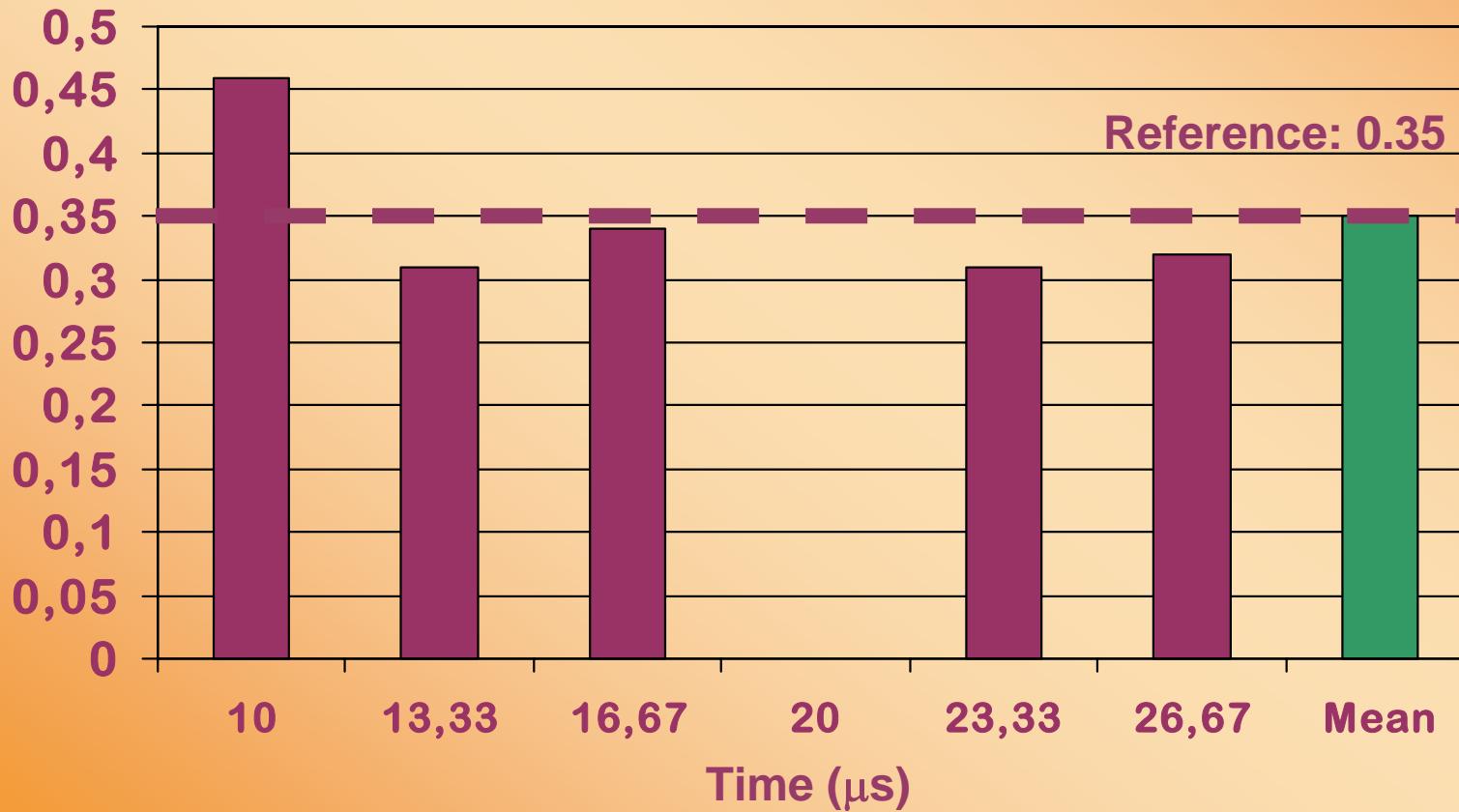
- Results

## Young's modulus (GPa)

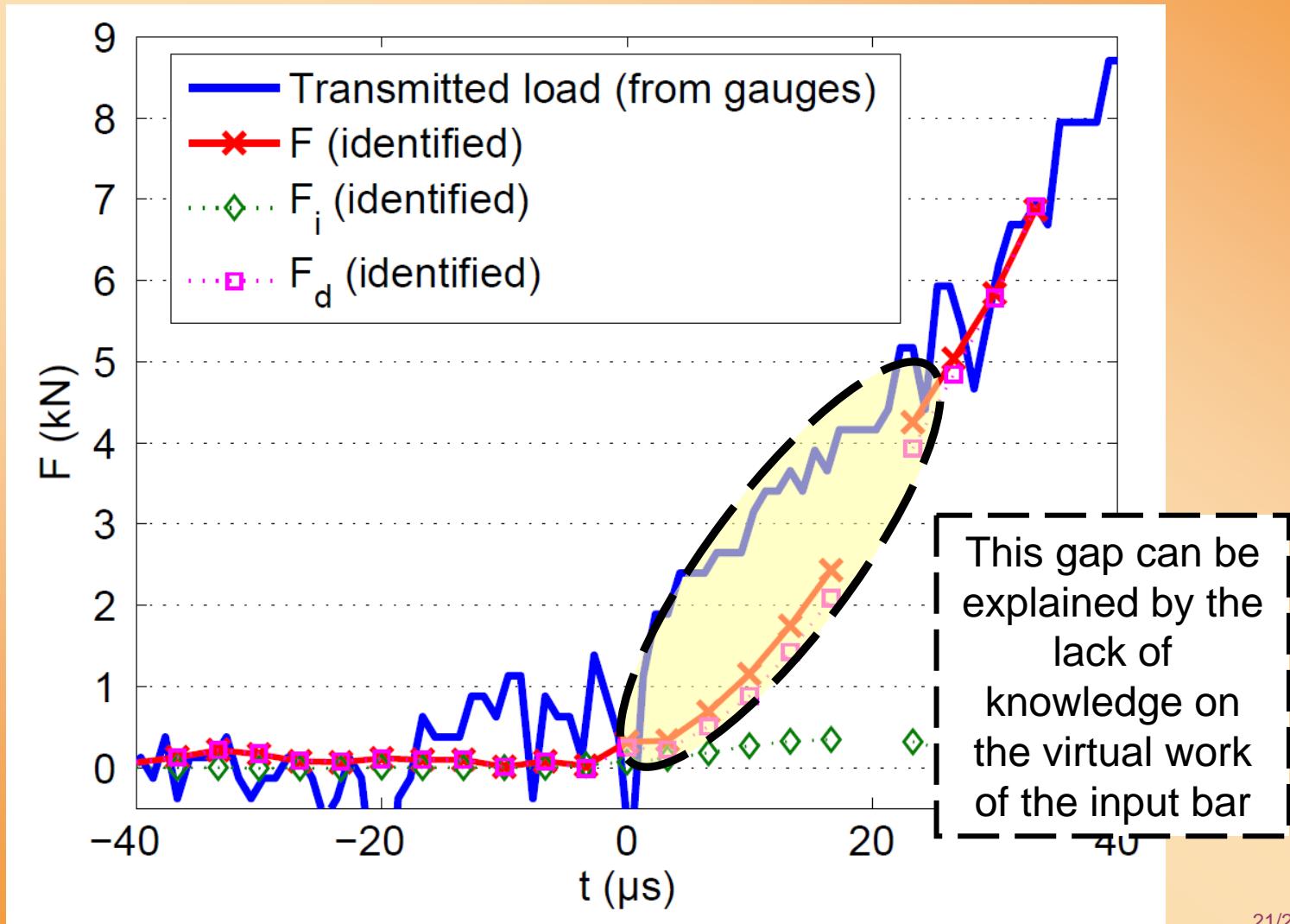


- Results

## Poisson's ratio



## ● Force reconstruction



# CONCLUSION

## ● Measurements

- Use of a UHS speed camera
- Quantitative data obtained (novel)
- Quality can be improved
  - ◆ Increase frame rate (limit: 4 Mfps)
  - ◆ Improve lighting, improve spatial resolution (grid pitch)
  - ◆ Understand origin of bias and noise

## ● Identification

- Quantitative data obtained
- Use of acceleration forces (novel)
- Huge future potential: no need for Hopkinson bar setup
- Need for better (and cheaper) cameras
- Need for new test designs

# ACKNOWLEDGEMENTS



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